

1/9

AMERICAN UNIVERSITY OF BEIRUT  
MATHEMATICS 218  
FALL SEMESTER 2009-2010  
FINAL EXAMINATION

Time: 120 minutes

Date: January 27, 2010

Name:.....

Solution

ID:.....

Circle your section number in the table below:

Instructors	Azar	Egeileh	El Khoury	Fuleihan	Karam	Nassif
Section	8	5	1	6	4	2
Section			3		9	7

QUESTION	GRADE
1	/25
2	/25
3	/25
4	/26
5	/30
6	/34
7	/35
TOTAL GRADE	/200

Answer the following seven sets of questions; the back of pages may be used as scratch.

1. Let  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^4$  be defined by:

$$T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} 2x + y + 3z \\ x + 2y \\ y + z \\ z \end{bmatrix}$$

- (a) Show that  $T$  is a linear transformation. (8 points)  
 (b) Show that  $T$  is one-to-one. (6 points)  
 (c) What is the rank of the matrix representing  $T$ . (4 points)  
 (d) Find a basis for the range of  $T$ . (7 points)

$$(a) T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{pmatrix} 2x + y + 3z \\ x + 2y \\ y + z \\ z \end{pmatrix} = \underbrace{\begin{pmatrix} 2 & 1 & 3 \\ 1 & 2 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}}_A \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$T$  is a matrix multiplication by the  $4 \times 3$  matrix  $A$ .  
 $T$  is therefore a linear transformation.

or For all  $u = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$  and  $v = \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix}$  in  $\mathbb{R}^3$ , and for all  $k \in \mathbb{R}$ ,  
 $u + kv = \begin{pmatrix} x + kx' \\ y + ky' \\ z + kz' \end{pmatrix}$  and  $T(u + kv) = \begin{pmatrix} 2(x + kx') + (y + ky') + (z + kz') \\ (x + kx') + 2(y + ky') \\ (y + ky') + (z + kz') \\ (z + kz') \end{pmatrix}$   
 yielding  $T(u + kv) = \begin{pmatrix} 2x + y + z \\ x + 2y \\ y + z \\ z \end{pmatrix} + k \begin{pmatrix} 2x' + y' + z' \\ x' + 2y' \\ y' + z' \\ z' \end{pmatrix} = T(u) + kT(v)$ .  
 Hence the linearity of  $T$ .

(b) Find the nullspace of  $T$ :  
 $\forall v \in N(T)$ ,  $v = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$  and is such that  $T(v) = 0 \Leftrightarrow \begin{pmatrix} 2x + y + z \\ x + 2y \\ y + z \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$

It follows:  $\begin{cases} 2x + y + z = 0 \\ x + 2y = 0 \\ y + z = 0 \\ z = 0 \end{cases}$  which is a homogeneous linear system having only the trivial solution  $x = y = z = 0$

Therefore  $N(T) = \{0\} \subset \mathbb{R}^3 \Leftrightarrow T$  is one-to-one.

(c) Find a row-echelon form of  $A$ :

$$\begin{pmatrix} 2 & 1 & 3 \\ 1 & 2 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & 1 & 3 \\ 0 & 3/2 & -3/2 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & 1 & 3 \\ 0 & 3/2 & -3/2 \\ 0 & 0 & 2 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & 1 & 3 \\ 0 & 3/2 & -3/2 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

The rank of the matrix  $A$ , representing the linear transformation, is equal to the common dimension of  $\text{col}(A)$  and  $\text{row}(A)$ .  
 Since the obtained row-echelon form has 3 leading entries, one concludes that  $\text{rank}(A) = 3$ .

(d) Range of  $T$ :  $R(T) = \text{col}(A)$  ( $T$  being a matrix multiplication by  $A$ )  
 Basis for  $R(T)$ :  $B = \left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\}$  (columns of  $A$  corresponding to the leading entries of its row-echelon form)

2. Let  $A = \begin{pmatrix} 1 & 2 & -1 & 1 \\ 2 & 4 & -3 & 3 \\ 3 & 5 & -6 & -5 \end{pmatrix}$

- (a) Find a basis for the  $N(A)$ . (10 points)  
 (b) Determine a basis for  $N(A)^\perp$  with respect to the Euclidean inner product. (7 points)  
 (c) What is the dimension of  $N(A^T)$ ? (8 points)

(a)  $N(A) = \{x \in \mathbb{R}^4, Ax = 0\}$

$$Ax = 0 \Leftrightarrow \begin{pmatrix} 1 & 2 & -1 & 1 \\ 2 & 4 & -3 & 3 \\ 3 & 5 & -6 & -5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Row-echelon form of  $A$ :

$$A \rightarrow \begin{pmatrix} 1 & 2 & -1 & 1 \\ 0 & 0 & -1 & 1 \\ 0 & -1 & -3 & -8 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & -1 & 1 \\ 0 & -1 & -3 & -8 \\ 0 & 0 & -1 & 1 \end{pmatrix} = R$$

$$\therefore Ax = 0 \Leftrightarrow \begin{cases} x_1 + 2x_2 - x_3 + x_4 = 0 \\ -x_2 - 3x_3 - 8x_4 = 0 \\ -x_3 + x_4 = 0 \end{cases}$$

let  $x_4 = t$   
 then  $x_3 = t$   
 $x_2 = -11t$   
 $x_1 = 22t$

$$x \in N(A) \Leftrightarrow x = t \begin{pmatrix} 22 \\ -11 \\ 1 \\ 1 \end{pmatrix} \quad t \in \mathbb{R}$$

yielding  $N(A) = \text{span} \left\{ \begin{pmatrix} 22 \\ -11 \\ 1 \\ 1 \end{pmatrix} \right\}$

$B = \{u_1\}$  is a basis for  $N(A)$ .  $\rightarrow u_1 \in \mathbb{R}^4$

(b) The orthogonal complement of  $N(A)$  is the row space of  $A$ :  
 $N(A)^\perp = \text{row}(A)$ .

Therefore, a basis for  $N(A)^\perp$  is a basis for  $\text{row}(A)$ .  
 Such basis could be made of the row of the row-echelon form of  $A$  containing the leading entries:

$$B' = \{u_2, u_3, u_4\} \quad \text{where } u_2 = \begin{pmatrix} 1 \\ -1 \\ -3 \\ -8 \end{pmatrix}, u_3 = \begin{pmatrix} 0 \\ -1 \\ -3 \\ -8 \end{pmatrix} \text{ and } u_4 = \begin{pmatrix} 0 \\ 0 \\ -1 \\ 1 \end{pmatrix}$$

(c) size  $(A) = 3 \times 4$

size  $(A^T) = 4 \times 3$

Therefore:  $\dim(N(A^T)) + \text{rank}(A^T) = 3$

But  $\text{rank}(A^T) = \text{rank}(A) = 3$  (common dimension of  $\text{col}(A)$  and  $\text{row}(A)$ )

It follows:

$$\dim N(A^T) = 0$$

or equivalently  $\text{nullity}(A^T) = 0$



3. Let  $A = \begin{pmatrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ -1 & -1 & 1 \end{pmatrix}$

- (a) Find the eigenvalues of  $A$ . (10 points)  
 (b) Find  $P$  that diagonalizes  $A$ . (10 points)  
 (c) Deduce  $P^{-1}AP$ . (5 points)

(a) The eigenvalues of  $A$  are the solutions of the characteristic equation:  $\det(A - \lambda I) = 0$

$$\begin{vmatrix} 1-\lambda & -1 & -1 \\ -1 & 1-\lambda & -1 \\ -1 & -1 & 1-\lambda \end{vmatrix} = 0 \quad \text{Expanding along the first row, it yields:}$$

$$(1-\lambda)[(1-\lambda)^2 - 1] + [\lambda - 1 - 1] - [1 + 1 - \lambda] = 0$$

$$-\lambda(1-\lambda)(2-\lambda) + 2(\lambda-2) = 0 \Leftrightarrow (\lambda-2)[\lambda(1-\lambda) + 2] = 0$$

$$\Leftrightarrow (\lambda-2)(-\lambda^2 + \lambda + 2) = 0 \Leftrightarrow \lambda - 2 = 0 \quad \text{or} \quad -\lambda^2 + \lambda + 2 = 0$$

$$\lambda = 2 \quad \text{or} \quad \lambda = -1 \quad \text{or} \quad \lambda = 2$$

(b) Find bases for the eigenspaces of  $A$ ; (then deduce  $P$ )

\* Eigenspace corresponding to  $\lambda_1 = 2$  (of algebraic multiplicity equal to 2)

This is the solution set of  $(A - \lambda_1 I)x = 0$

$$\begin{pmatrix} -1 & -1 & -1 \\ -1 & -1 & -1 \\ -1 & -1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

Row-reducing the augmented matrix:

$$\left( \begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ -1 & -1 & -1 & 0 \\ -1 & -1 & -1 & 0 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

makes the linear system equivalent to the unique linear equation:  $x_1 + x_2 + x_3 = 0$

Let  $x_3 = t$  and  $x_2 = s$ , then  $x_1 = -s - t$

$$\text{implying } \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -s-t \\ s \\ t \end{pmatrix} = s \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$\{v_1, v_2\}$  spans the eigenspace corresponding to  $\lambda_1 = 2$  and is linearly independent

$\therefore \{v_1, v_2\}$  is a basis for this eigenspace.

(making the geometric multiplicity of  $\lambda_1$  equal to its algebraic one)

\* Eigenspace corresponding to  $\lambda_2 = -1$

$$(A - \lambda_2 I)x = 0 \quad \left( \begin{array}{ccc|c} 2 & -1 & -1 & 0 \\ -1 & 2 & -1 & 0 \\ -1 & -1 & 2 & 0 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 2 & -1 & -1 & 0 \\ 0 & 3/2 & -3/2 & 0 \\ 0 & -3/2 & 3/2 & 0 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 2 & -1 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

Equivalent triangular system:  $\begin{cases} 2x_1 - x_2 - x_3 = 0 \\ x_2 - x_3 = 0 \end{cases}$

Let  $x_3 = t$ , then  $x_2 = t$  and  $x_1 = t$  implying  $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

$\{v_3\}$  is a basis for the eigenspace corresponding to  $\lambda_2 = -1$

\*  $P = (v_1 | v_2 | v_3) = \begin{pmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$  diagonalizes  $A$ ,

(c)

$$\text{and } P^{-1}AP = \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_1 & 0 \\ 0 & 0 & \lambda_2 \end{pmatrix} = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

4. (a) Without solving, find condition(s) on  $\alpha$  and  $\beta$  for the following system to have exactly one solution: (10 points)

$$\begin{cases} x + y + \alpha z = 1 \\ x + y + \beta z = 2 \\ \alpha x + \beta y + z = -1 \end{cases}$$

(b) For  $\alpha = \beta = 0$  find the least squares solution(s) of the linear system. (16 points)

(a) The given linear  $3 \times 3$  system has a unique solution iff the coefficient matrix is invertible, that is iff its determinant is nonzero:

$$\begin{aligned} \begin{vmatrix} 1 & 1 & \alpha \\ 1 & 1 & \beta \\ \alpha & \beta & 1 \end{vmatrix} \neq 0 &\iff [1 - \beta^2] - [1 - \alpha\beta] + \alpha[\beta - \alpha] \neq 0 \\ &\iff -\alpha^2 - \beta^2 + 2\alpha\beta \neq 0 \\ &\iff -(\alpha - \beta)^2 \neq 0 \\ &\iff \alpha - \beta \neq 0 \iff \boxed{\alpha \neq \beta} \end{aligned}$$

(b) For  $\alpha = \beta = 0$ , the linear system becomes:  $\begin{cases} x + y = 1 \\ x + y = 2 \\ z = -1 \end{cases}$

and is obviously inconsistent.

Its matrix form is:  $\underbrace{\begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}}_A \underbrace{\begin{pmatrix} x \\ y \\ z \end{pmatrix}}_X = \underbrace{\begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}}_b$

Any least squares solution to this linear system is the exact solution to the corresponding normal system:  $A^T A X = A^T b$  (Here  $A^T = A$ )

Find  $A^T A$ :  $\begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 2 & 0 \\ 2 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$  and  $A^T b$ :  $\begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$

Row-reducing the augmented matrix of  $A^T A X = A^T b$ :  $\left( \begin{array}{ccc|c} 2 & 2 & 0 & 3 \\ 2 & 2 & 0 & 3 \\ 0 & 0 & 1 & -1 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 2 & 2 & 0 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 2 & 2 & 0 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{array} \right)$   
 yields the equivalent triangular linear system:  
 $\begin{cases} 2x_1 + 2x_2 = 3 \\ x_3 = -1 \end{cases}$  let  $x_2 = t$   
 then  $x_1 = \frac{1}{2}(3 - 2t) = \frac{3}{2} - t$

Hence, the given system has infinitely many least squares solutions of the form:

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \frac{3}{2} - t \\ t \\ -1 \end{pmatrix} = \begin{pmatrix} 3/2 \\ 0 \\ -1 \end{pmatrix} + t \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \text{ where } t \in \mathbb{R}$$



5. Let  $W = \{p(x) \in P_3 / xp(2) - p(1) = 0\}$

(a) Prove that  $W$  is a subspace of  $P_3$ . (8 points)

(b) Find a basis for  $W$ . (12 points)

(c) Let  $T : P_3 \rightarrow P_1$  be the linear transformation defined by:

$$T(p(x)) = xp(2) - p(1)$$

Show that  $T$  is onto. (10 points)

(a)  $W$  subspace of  $P_3$

$$\forall p, q \in W, \forall k \in \mathbb{R}, \\ x[(p+kq)(2)] - (p+kq)(1) = x[p(2) + kq(2)] - p(1) - kq(1) \\ = [xp(2) - p(1)] + k[xq(2) - q(1)] \\ = 0 \quad \text{since } p, q \in W$$

Hence,  $(p+kq) \in W$  meaning that  $W$  is closed under addition and scalar multiplication and therefore a subspace of  $P_3$ .

(b) Basis for  $W$ ; Find first vectors (polynomials) spanning  $W$ .

$$\forall p \in W, p(x) \text{ is of the form } p(x) = a_0 + a_1x + a_2x^2 + a_3x^3 \\ \text{with } p(2) = a_0 + 2a_1 + 4a_2 + 8a_3 \\ p(1) = a_0 + a_1 + a_2 + a_3$$

and  $xp(2) - p(1) = 0$  (zero-polynomial)  
 i.e.  $(a_0 + 2a_1 + 4a_2 + 8a_3)x - (a_0 + a_1 + a_2 + a_3) = 0 \quad (\forall x \in \mathbb{R})$   
 using the identity property:  $\begin{cases} a_0 + a_1 + a_2 + a_3 = 0 \\ a_0 + 2a_1 + 4a_2 + 8a_3 = 0 \end{cases}$

$$\left( \begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 1 & 2 & 4 & 8 & 0 \end{array} \right) \rightarrow \left( \begin{array}{cccc|c} 1 & 1 & 1 & 1 & 0 \\ 0 & 1 & 3 & 7 & 0 \end{array} \right)$$

$$\Leftrightarrow \begin{cases} a_0 + a_1 + a_2 + a_3 = 0 \\ a_1 + 3a_2 + 7a_3 = 0 \end{cases}$$

Setting  $a_3 = t$  and  $a_2 = 1$  yields  $a_1 = -3s - 7t$  and  $a_0 = 2s + 7t$   
 Therefore,  $p(x) = (2s + 7t) + (-3s - 7t)x + 1x^2 + tx^3$   
 $= s(2 - 3x + x^2) + t(7 - 7x + x^3)$

Let  $b_1(x) = 2 - 3x + x^2$  and  $b_2(x) = 7 - 7x + x^3$ .  
 Then,  $\forall p \in W, p = sb_1 + tb_2$  where  $s, t \in \mathbb{R}$

i.e.  $\{b_1, b_2\}$  span  $W$ .  
 But  $b_1$  and  $b_2$  are linearly independent (distinct degrees)  
 Therefore  $\{b_1, b_2\}$  is a basis for  $W$ .

(c)  $T(p(x)) = xp(2) - p(1) \quad \forall p \in P_3$

$T$  is onto

Note first that  $W = N(T)$  (nullspace of  $T$ ),  
 since  $W = \{p(x) \in P_3 / T(p(x)) = 0\}$

And  $\dim(W) = 2$  yielding  $\dim(N(T)) = 2$

Knowing that  $\dim(N(T)) + \dim(R(T)) = \dim(P_3)$   
 it follows:  $2 + \dim(R(T)) = 4 \Leftrightarrow \dim(R(T)) = 2$

But  $R(T)$  is a subspace of  $P_1$  and  $\dim(P_1) = 2 = \dim(R(T))$   
 Therefore,  $R(T) = P_1 \Leftrightarrow T$  is onto.

6. Let  $P_2$  be the set of polynomials of degree less or equal than 2. Define the inner product on  $P_2$  by:

$$\langle p, q \rangle = a_0b_0 + a_1b_1 + a_2b_2$$

where  $p(x) = a_0 + a_1x + a_2x^2$  and  $q(x) = b_0 + b_1x + b_2x^2$ .

Let  $p(x) = 1 + x$ ,  $q(x) = 1 + 2x^2$  and  $W = \text{span}\{p, q\}$

- (a) Find  $\lambda$  such that  $(q - \lambda p)$  and  $p$  are orthogonal. (6 points)
- (b) Show that  $\{p, q\}$  is a basis for  $W$ . (4 points)
- (c) Use the Gram-Schmidt process to find an orthogonal basis for  $W$ . (10 points)
- (d) Find a basis for  $W^\perp$ . (10 points)
- (e) Deduce an orthogonal basis for  $P_2$ . (4 points)

(a)  $(q - \lambda p)$  and  $p$  are orthogonal  $\Leftrightarrow \langle q - \lambda p, p \rangle = 0$

$\Leftrightarrow \langle q, p \rangle - \lambda \langle p, p \rangle = 0$   
 with  $\begin{cases} p(x) = 1+x \\ q(x) = 1+2x^2 \end{cases}$  yielding:  $\begin{cases} \langle p, q \rangle = 1 \\ \langle p, p \rangle = 2 = \|p\|^2 \end{cases}$   
 $\lambda$  should then satisfy:  $1 - 2\lambda = 0 \Leftrightarrow \lambda = \frac{1}{2}$

(b)  $\{p, q\}$  basis for  $W = \text{span}\{p, q\}$

Consider the vector equation:  $k_1p + k_2q = 0$   
 i.e.  $\forall x \in \mathbb{R}, k_1(1+x) + k_2(1+2x^2) = 0$   
 $(k_1+k_2) + k_1x + 2k_2x^2 = 0$

It follows:  $\begin{cases} k_1+k_2=0 \\ k_1=0 \\ 2k_2=0 \end{cases}$  and therefore  $k_1=k_2=0$ ,

making  $\{p, q\}$  linearly independent and therefore a basis for  $W$ .

(c) Orthogonal basis for  $W$ : let  $\{b_1, b_2\}$  be such basis.

Using the Gram-Schmidt process:

- $b_1 = p = 1+x$
- $b_2 = q - \text{proj}_{b_1} q = q - \frac{\langle q, b_1 \rangle}{\|b_1\|^2} b_1 = 1+2x^2 - \frac{1}{2}(1+x) = \frac{1}{2} - \frac{1}{2}x + 2x^2$

$\therefore \{b_1, b_2\} = \{1+x, \frac{1}{2} - \frac{1}{2}x + 2x^2\}$  is an orthogonal basis for  $W$ .

(d) Basis for  $W^\perp = (\{p, q\})^\perp$

Since  $\{p, q\}$  is a basis for  $W$ , then:

$v \in W^\perp \Leftrightarrow \begin{cases} \langle v, p \rangle = 0 \\ \langle v, q \rangle = 0 \end{cases}$   
 Let  $v = c_0 + c_1x + c_2x^2$ , yielding  $\begin{cases} \langle v, p \rangle = c_0 + c_1 \\ \langle v, q \rangle = c_0 + 2c_2 \end{cases}$   
 So  $v \in W^\perp \Leftrightarrow \begin{cases} c_0 + c_1 = 0 \\ c_0 + 2c_2 = 0 \end{cases}$

$\begin{pmatrix} 1 & 1 & 0 & | & 0 \\ 1 & 0 & 2 & | & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 & | & 0 \\ 0 & -1 & 2 & | & 0 \end{pmatrix}$  yielding the equivalent system  $\begin{cases} c_0 + c_1 = 0 \\ -c_1 + 2c_2 = 0 \end{cases}$

Let  $c_2 = t$ , then  $c_1 = 2t$  and  $c_0 = -2t$ .  
 So that:  $v \in W^\perp \Leftrightarrow v = -2t + 2tx + tx^2 = t(-2 + 2x + x^2)$   
 $\{b_3\} = \{-2 + 2x + x^2\}$  is a basis for  $W^\perp$

(e)  $b_3 \in W^\perp$  and  $\{b_1, b_2\}$  is an orthogonal basis for  $W$   
 then  $\langle b_3, b_1 \rangle = 0$  and  $\langle b_3, b_2 \rangle = 0$ , with  $\langle b_1, b_2 \rangle = 0$   
 It follows that  $\{b_1, b_2, b_3\} = \{1+x, \frac{1}{2} - \frac{1}{2}x + 2x^2, -2 + 2x + x^2\}$  is an orthogonal basis for  $P_2 = W \oplus W^\perp$ .

7. Prove the following statements:

(a)  $T: V \rightarrow V$  such that  $T$  is one-to-one, prove that if  $\{v_1, \dots, v_n\}$  are linearly independent in  $V$ , then  $\{T(v_1), \dots, T(v_n)\}$  are linearly independent. (10 points)

Consider the vector equation:

$$\begin{aligned}
 & c_1 T(v_1) + \dots + c_n T(v_n) = 0 \\
 \Rightarrow & T(c_1 v_1 + \dots + c_n v_n) = 0 \quad \left. \begin{array}{l} \text{ } \\ \text{ } \end{array} \right\} \begin{array}{l} T \text{ linear} \\ T \text{ one-to-one} \end{array} \\
 \Rightarrow & c_1 v_1 + \dots + c_n v_n = 0 \\
 \Rightarrow & c_1 = \dots = c_n = 0 \\
 \text{Therefore } & c_1 T(v_1) + \dots + c_n T(v_n) = 0 \text{ has only the trivial} \\
 \text{solution, making } & \{T(v_1), \dots, T(v_n)\} \text{ linearly independent.}
 \end{aligned}$$

(b) Let  $V$  be an inner product space. Show that:

$$\|u\| = \|v\| \Leftrightarrow u+v \text{ and } u-v \text{ are orthogonal}$$

(10 points)

$$\begin{aligned}
 \underline{u+v \text{ and } u-v \text{ are orthogonal}} & \Leftrightarrow \langle u+v, u-v \rangle = 0 \\
 & \Leftrightarrow \langle u, u \rangle + \langle v, u \rangle - \langle u, v \rangle - \langle v, v \rangle = 0 \\
 & \Leftrightarrow \|u\|^2 + 0 - 0 - \|v\|^2 = 0 \\
 & \Leftrightarrow \|u\|^2 = \|v\|^2 \\
 & \Leftrightarrow \boxed{\|u\| = \|v\|} \quad \text{since norms of vectors are positive numbers.}
 \end{aligned}$$



(c) Let  $B$  be an  $n \times n$  invertible matrix and  $T : M_{n \times n} \rightarrow M_{n \times n}$  be defined by  $T(A) = AB$ . Show that  $T$  is an isomorphism. (15 points)

\*  $T$  is a linear transformation:

$$\forall A_1, A_2 \in M_{n \times n}, \quad \forall k \in \mathbb{R},$$

$$\begin{aligned} T(A_1 + kA_2) &= (A_1 + kA_2)B \\ &= A_1B + kA_2B \\ &= T(A_1) + kT(A_2) \end{aligned}$$

Hence the linearity of  $T$

\*  $T$  is one-to-one: Let  $N(T)$  be the nullspace of  $T$ .

$$\forall A \in N(T), \quad T(A) = 0 \quad \Leftrightarrow \quad AB = 0$$

but  $B$  is invertible, so  $ABB^{-1} = 0B^{-1}$

$$\therefore N(T) = \{0\} \quad \text{making } T \text{ one-to-one.} \quad \boxed{A=0} \quad (\text{zero-matrix})$$

\*  $T$  is onto:

$$\forall M \in M_{n \times n}, \quad \text{if there exists a matrix } A \text{ such that}$$

$$T(A) = M, \quad \text{then } AB = M \quad \Rightarrow \quad \underline{A = MB^{-1}}$$

B invertible

$\therefore$  Every matrix  $M$  has a preimage in  $M_{n \times n}$  which is  $A = MB^{-1}$

\* Therefore,  $T$  is an isomorphism.